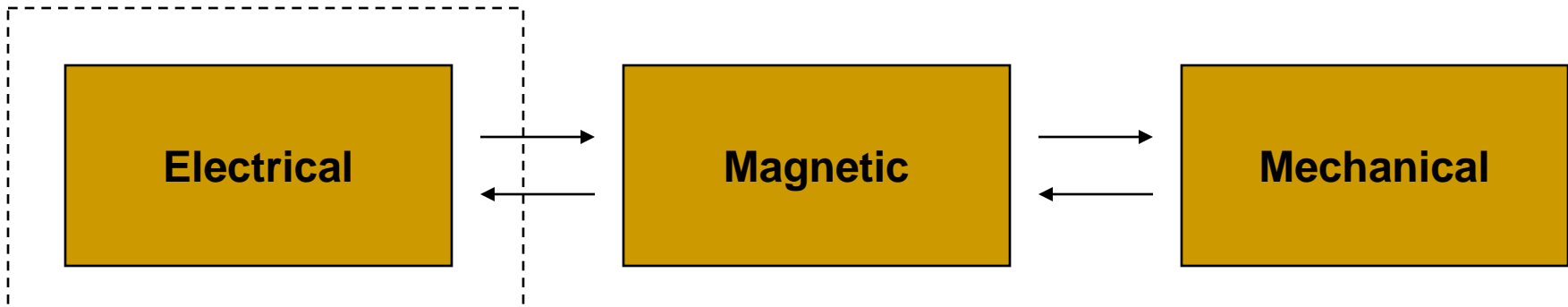


Linear Magnetostrictive Models in Comsol

Comsol Conference 2009
October 8-10, 2009
Boston, MA

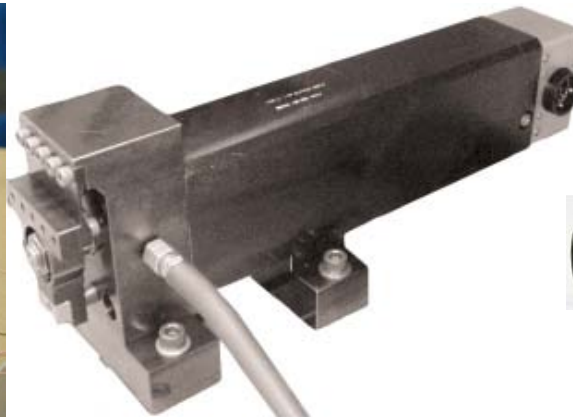
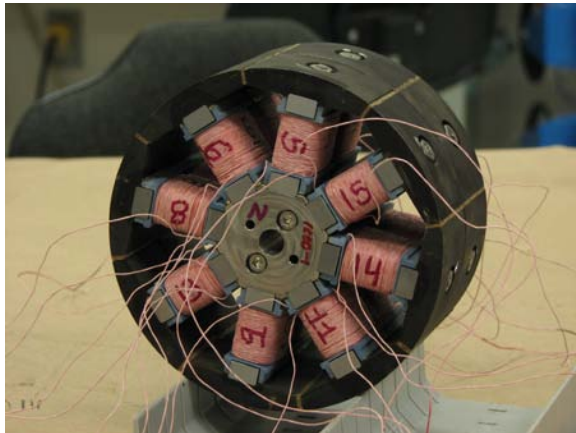
- Magnetostriction
- Equations
- Comsol models
- Examples
- Conclusions

- Coupling between magnetic and mechanical fields in a particular type of material
 - Mechanical response to a magnetic input
 - Magnetic response to a mechanical input
- Multi-physics coupling makes it ideal for modeling with Comsol



Uses of magnetostrictive materials

- Sonar, micro-positioning, ultrasonic processing, energy harvesting
- Typical transducers consist of magnets, coils, high flux materials, and mechanical interface
- Operated at a single frequency or across a broad frequency band

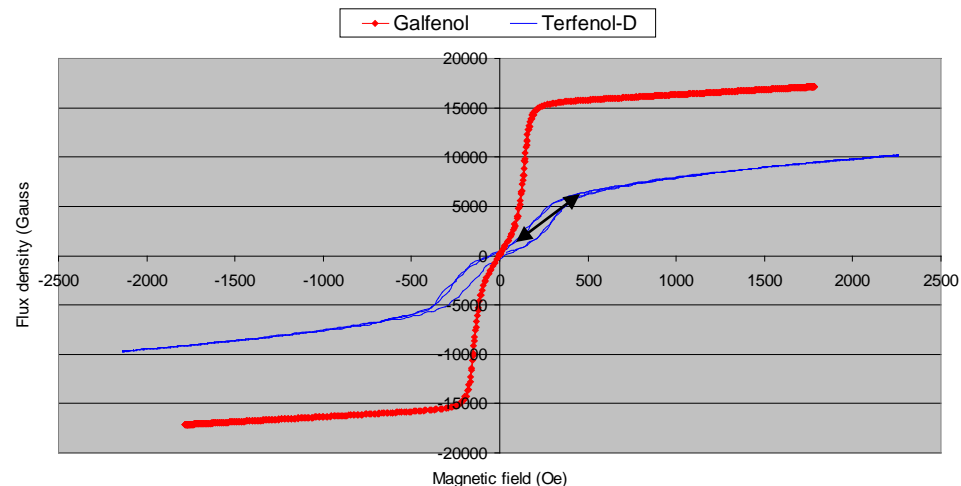
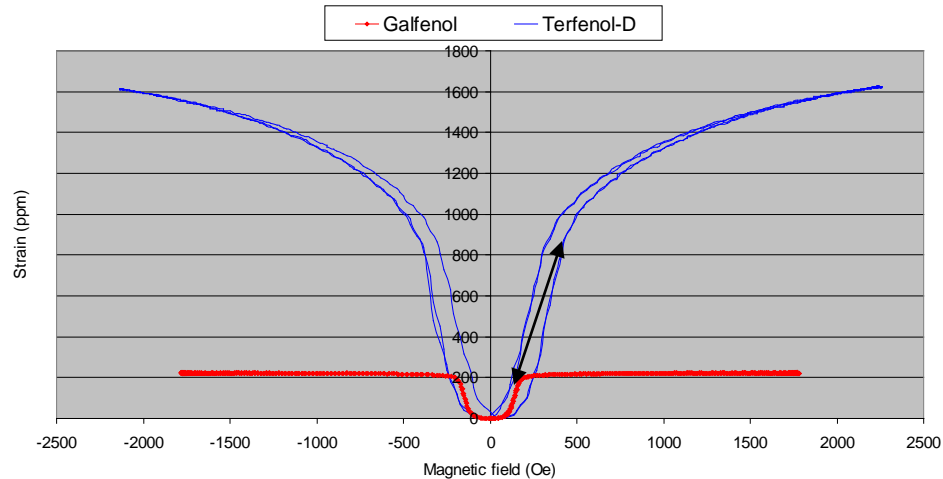


- Magnetostriction is coupling between the magnetic and mechanical domains in a material
 - Joule effect – change in shape of a material in response to a magnetic field
 - Villari effect – change in magnetic state of a material in response to an applied stress
- Magnetostriction is caused by magnetic domain wall motion and domain rotation
 - Magnetic domains are inherent to the material crystal structure
 - Several common materials exhibit magnetostriction including iron and nickel (on the order of 15-30 microstrain)
- Materials that exhibit extraordinary amounts of magnetostriction are referred to as “giant” magnetostrictive materials



Giant magnetostrictive materials

- Terfenol-D (TbFeDy alloys)
 - Up to 2000 microstrain
 - Saturates at ~1500 Oe
 - Very high energy density
 - Brittle, crystalline material, must be used in compression
- Galfenol (FeGa alloys)
 - Up to 400 microstrain
 - Saturates at ~150 Oe
 - Not as high energy density as Terfenol-D
 - Structural material, machinable, weldable, can be used in tension
- Nonlinear behavior - typically operated with a magnetic bias and a relatively small AC field to get bi-directional motion



Linear magnetostrictive equations

- Full 3D magnetostrictive equations

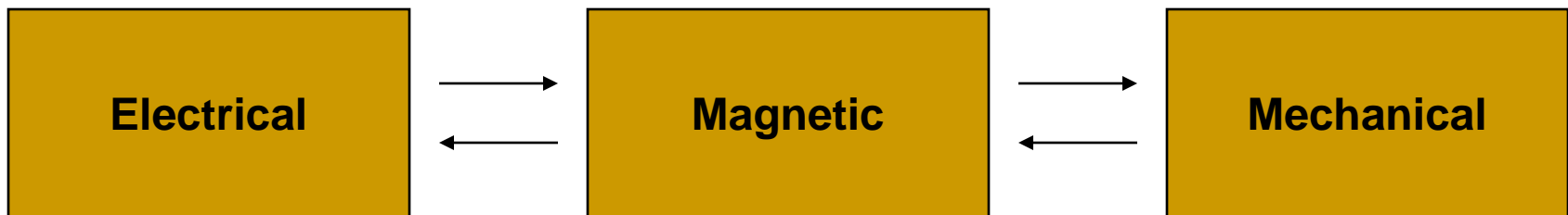
$$T = c^B S - h_t B$$

$$H = -hS + \gamma^S B$$

- T is stress, c^B is the compliance matrix with constant magnetic flux density, S is strain, h and h_t are magnetostrictive coupling coefficients, H is magnetic field, B is flux density, and γ^S is the inverse of permeability

■ Joule effect

- Electrical input – voltage or current into a coil
- Magnetic fields are generated
- Magnetostrictive material strains (displaces)

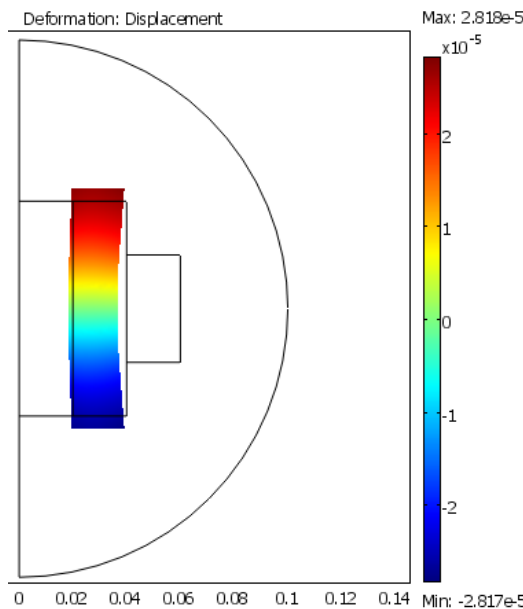


■ Villari effect

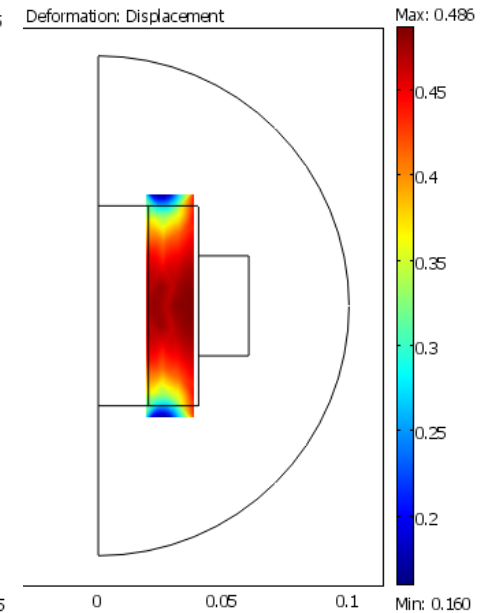
- Mechanical input (stress or strain) to the magnetostrictive material
- Magnetic fields are generated
- Electric fields are generated in a coil

- Comsol modules
 - Structural mechanics module – alternatively Acoustics or MEMS could be used
 - AC/DC module
- Magnetostrictive model was implemented by modifying the stress and magnetic field variables
 - $-h_f B$ in the stress variables
 - $-hS$ in the magnetic field variables
- Electrical impedance can be calculated using input voltage or current and the induced electric fields in the coil (measure of the transducer behavior)

- Simple model of material, air, and coil
- Used to verify Joule effect and Villari effect
- Shows expected magnitude of response



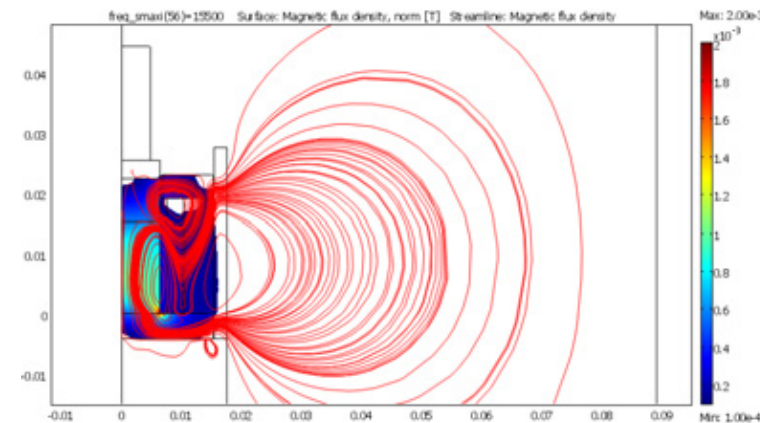
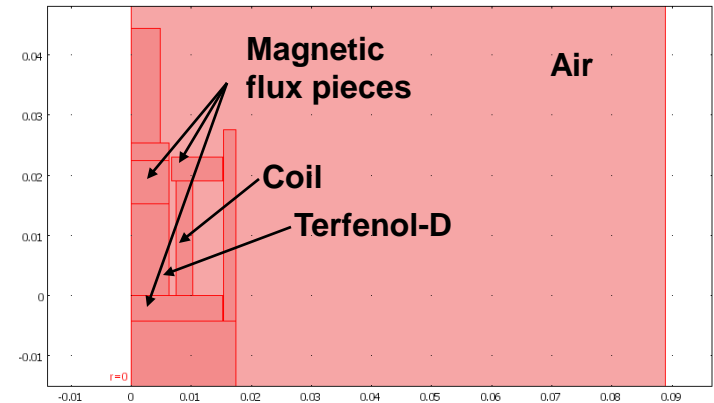
Joule effect



Villari effect

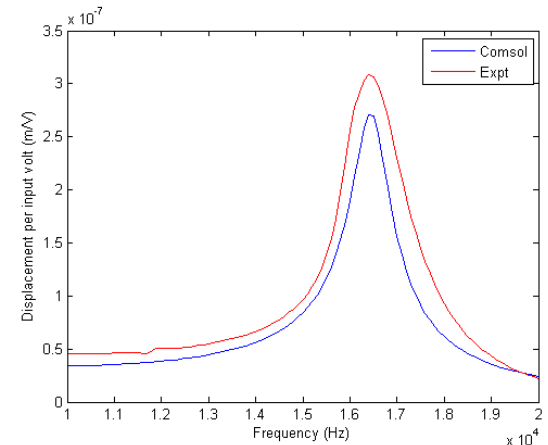
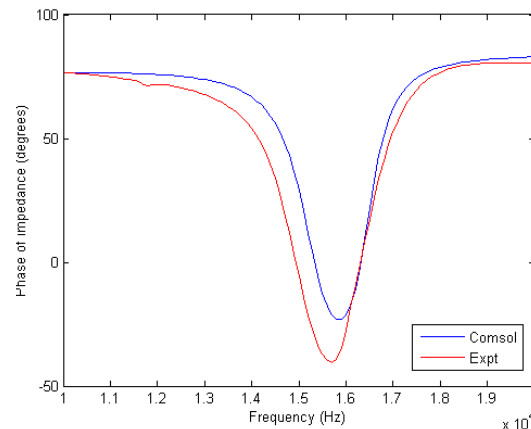
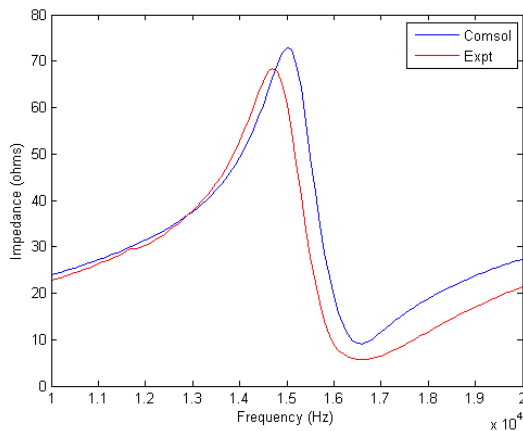
2D axisymmetric model of a transducer

- An existing Terfenol-D transducer was modeled with a 2D axisymmetric representation and a 1V input to the coil
- A harmonic solution from 10-20 kHz was performed in order to capture the resonance around 15.5 kHz

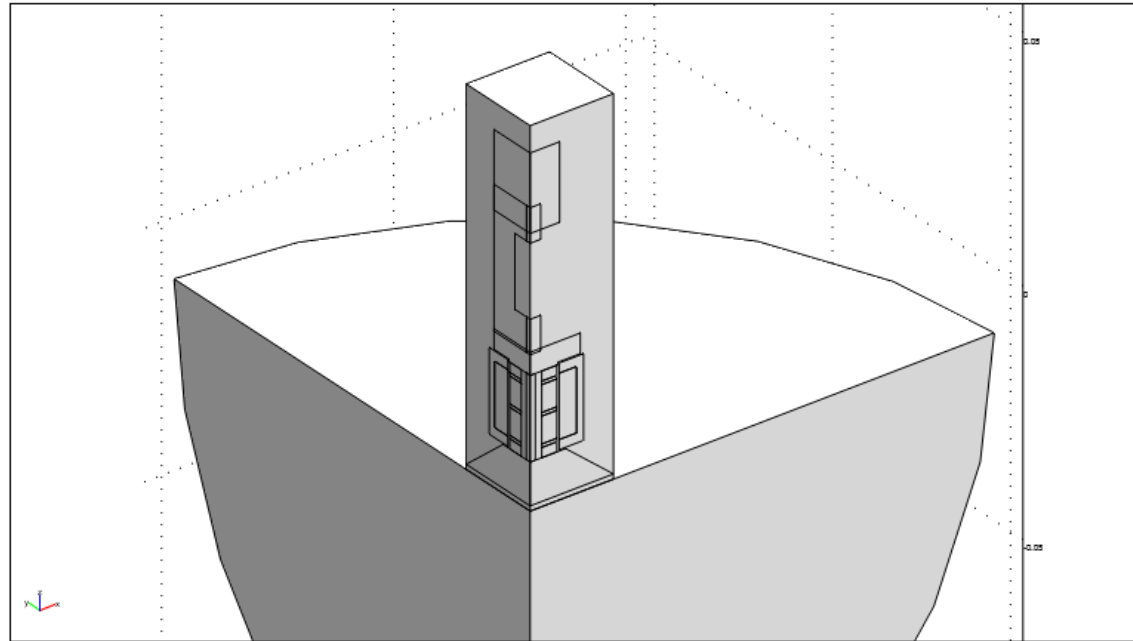


Impedance and displacement results

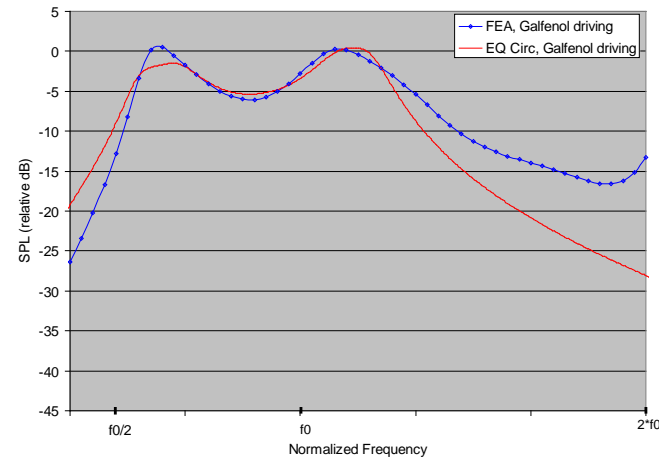
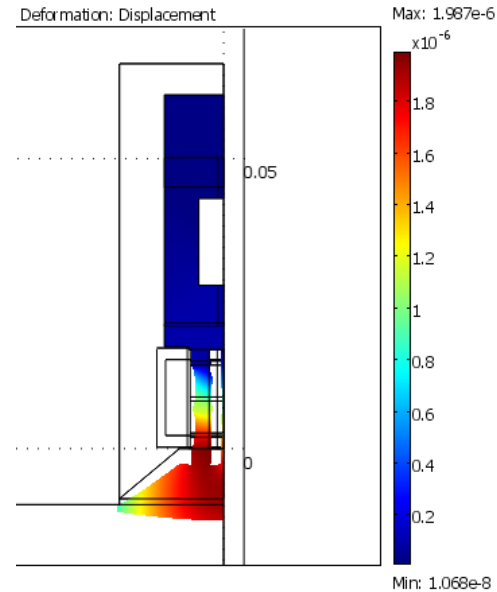
- Comparisons of experimental data and Comsol results show very good agreement
- Impedance and phase are very similar
- Magnitude of displacement is close



- Terfenol-D and Galfenol in the same transducer
- Not axisymmetric – 3D is necessary for modeling
- Includes a water load on the transducer face



- Driving only the lower (Terfenol-D) section
- Acoustic source level calculations match equivalent circuit predictions
 - Equivalent circuit models are a 1D model and do not capture complicated motion of the head mass
 - Displacement show that the head mass is starting to “flap” which affects the high frequency output



Conclusions and Future Work

- Models do a very good job of capturing behavior of magnetostrictive transducers
- 2D and 3D models are working fine and have reasonable solution times (a few minutes for 2D, 1-2 hours for 3D)
- Future work will focus on
 - Calculating impedance for 3D models
 - Validating more results against test data
 - Expanding to nonlinear material behavior